

Soft starter, 3p, 650A, Ue= 575-690VAC

 Part no.
 \$811+V65V3\$

 Article no.
 169004

 Catalog No.
 \$811PLU\$V65V3\$



Delivery program

| Zonio, program | | | |
|--|-----------------|------|---|
| Description | | | With internal bypass contacts |
| Function | | | Soft starter for three-phase loads, with control unit and pump algorithm, for 690-V grids |
| Mains supply voltage (50/60 Hz) | U _{LN} | V AC | 200 - 690 |
| Supply voltage | U_s | | 24 V DC |
| Control voltage | U _C | | 24 V DC |
| Assigned motor rating (Standard connection, In-Line) | | | |
| at 400 V, 50 Hz | P | kW | 315 |
| at 690 V, 50 Hz | P | kW | 630 |
| at 460 V, 60 Hz | P | HP | 500 |
| Rated operational current | | | |
| AC-53 | l _e | Α | 650 |
| Startup class | | | CLASS 10 (star-delta replacement) CLASS 20 (heavy starting duty 3 x I_e for 45 s) CLASS 30 (6 x I_e for 30 s) |
| Rated operational voltage | U _e | | 200 V 230 V 400 V 480 V 600 V 690 V |
| Connection to SmartWire-DT | | | no |
| Frame size | | | V |
| Ordering information | | | Terminal blocks for the terminals are required for frame sizes T, U, and V -> $\mbox{\sc Accessories}$ |

Technical data

General

| Standards | | | IEC/EN 60947-4-2 UL 508 CSA22.2-14-1995 GB14048 |
|--|----------|----|---|
| Approvals | | | CE |
| Approvals | | | UL CSA C-Tick CCC |
| Climatic proofing | | | Damp heat, constant, to IEC 60068-2-3 Damp heat, cyclic, to IEC 60068-2-10 |
| Ambient temperature | | | |
| Operation | 9 | °C | -30 - +50 |
| Storage | 9 | °C | -50 - +70 |
| Altitude | | m | 0 - 2000 m, above that each 100 m 0.5% Derating |
| Mounting position | | | As required |
| Degree of protection | | | |
| Degree of Protection | | | IP20 (terminals IP00) |
| Integrated | | | Protection type IP40 can be achieved on all sides with covers SS-IP20-N. |
| Protection against direct contact | | | Finger- and back-of-hand proof |
| Overvoltage category/pollution degree | | | 11/3 |
| Shock resistance | | | 15 g |
| Radio interference level (IEC/EN 55011) | | | A |
| Static heat dissipation, non-current-dependent | P_{vs} | W | 25 |
| Weight | | kg | 41.4 |

Main conducting paths

| Main conducting paths | | V.40 | 222 222 |
|--|------------------|------------------|--|
| Rated operating voltage | U _e | V AC | 200 - 690 |
| Supply frequency | f _{LN} | Hz | 50/60 |
| Rated operational current | le | Α | |
| AC-53 | I _e | Α | 650 |
| Assigned motor rating (Standard connection, In-Line) | | | |
| at 230 V, 50 Hz | P | kW | 200 |
| at 400 V, 50 Hz | P | kW | 315 |
| at 500 V, 50 Hz | P | kW | 450 |
| at 690 V, 50 Hz | P | kW | 630 |
| at 200 V, 60 Hz | P | HP | 200 |
| at 230 V, 60 Hz | P | HP | 250 |
| at 460 V, 60 Hz | P | HP | 500 |
| at 600 V, 60 Hz | P | HP | 600 |
| at 690 V, 60 Hz | P | HP | 750 |
| Assigned motor rating (delta connection) | | | |
| at 690 V, 60 Hz | P | HP | 1300 |
| Overload cycle to IEC/EN 60947-4-2 | | | |
| AC-53a | | | 650 A: AC-53a: 4.0 - 32: 99 - 3 |
| Internal bypass contacts | | | 1 |
| Chart aircuit rating | | | |
| Short-circuit rating Type "1" coordination | | | NZMN4-ME875 |
| Terminal capacities | | | NZIVIN4-IVIE673 |
| Cable lengths | | | |
| Solid | | mm ² | 2 x (120 - 240) |
| | | 111111 | 4 x (70 - 240) |
| Flexible with ferrule | | 2 | 6 x (120 - 240) 2 x (120 - 240) |
| riexible with letture | | mm ² | 4 x (70 - 240) |
| | | | 6 x (120 - 240) |
| Stranded | | mm ² | 2 x (120 - 240) 4 x (70 - 240) |
| | | | 6 x (120 - 240) |
| Solid or stranded | | AWG | 2 x (4 - 500 kcmil) 4 x (4 - 500 kcmil) |
| | | | 6 x (4 - 500 kcmil) |
| Control cables | | | |
| Solid | | mm ² | 1 x (2.5 - 4) |
| | | | 2 x (1.0 - 2.5) |
| Flexible with ferrule | | mm ² | 1 x (2.5 - 4) 2 x (1.0 - 2.5) |
| Stranded | | mm ² | 1 x (2.5 - 4) |
| | | | 2 x (1.0 - 2.5) |
| Solid or stranded | | AWG | 38 x (12 - 14) 2 x (12 - 14) |
| Tightening torque | | Nm | 0.4 |
| Screwdriver | | mm | 0,6 x 3,5 |
| Control circuit | | | op . ap |
| Digital inputs | | | |
| Control voltage | | | |
| DC-operated | | V DC | 24 V DC +10 %/- 10 % |
| Current consumption 24 V | | mA | |
| External 24 V | | mA | 150 |
| External 24 V (no-load) | | mA | 100 |
| Pick-up voltage | | x U _s | |
| DC-operated | | V DC | 21.6 - 26.4 |
| Drop-out voltage | x U _s | | |
| DC operated | - 5 | V DC | |
| Drop-out voltage, DC-operated, max. | | V DC | 2 |
| | | V DC | 3 |
| Pick-up time | | | |

| DC operated | | ms | 100 |
|---|-------------------|--------|--|
| Drop-out time | | IIIO | |
| DC operated | | ms | 100 |
| Regulator supply | | | |
| Voltage | U _s | V | 24 V DC +10 %/- 10 % |
| Current consumption | I _e | mA | 1400 |
| Current consumption at peak performance (close bypass) at 24 V DC | | | |
| | I _{Peak} | A/ms | 10/150 |
| Notes | | | External supply voltage |
| Analog inputs | | | |
| Number of current inputs | | | 1 |
| Current input | | mA | 4 - 20 |
| Relay outputs | | | |
| Number | | | 2 |
| of which programmable | | | 2 |
| Voltage range | | V AC | 120 V AC/DC |
| AC-11 current range | | Α | 3 A, AC-11 |
| Soft start function | | | |
| Ramp times | | | |
| Acceleration | | S | |
| Ramp time, max. | | S | 360 |
| Deceleration | | S | 0 - 120 |
| Start voltage (= turn-off voltage) | | % | |
| Start voltage, max. | | % | 85 |
| Start pedestal | | % | |
| Start voltage, max. | | % | 85 |
| Kickstart | | | |
| Voltage | | % | |
| Kickstart voltage, max. | | % | 100 |
| Duration | | | |
| 50 Hz | | ms | |
| Kickstart Duration 50 Hz max. | | ms | 2000 |
| 60 Hz | | ms | |
| Kickstart Duration 60 Hz max. | | ms | 2000 |
| Fields of application | | | |
| Fields of application | | | Soft starting of three-phase asynchronous motors |
| 3-phase motors | | | 1 |
| Functions Fast switching (semiconductor contactor) | | | - (minimum ramp time 1s) |
| Soft start function | | | - (minimum ramp time is) |
| Reversing starter | | | External solution required (reversing contactor) |
| Suppression of closing transients | | | 1 |
| Current limitation | | | ✓ |
| Overload monitoring | | | 1 |
| Underload monitoring | | | ✓ |
| Fault memory | | Faults | 10 |
| Suppression of DC components for motors | | | ✓ |
| Potential isolation between power and control sections | | | ✓ |
| | | | |
| Communication Interfaces | | | Modbus RTU |

| D | esian | verification | as | per | IEC | /EN | 61439 | 9 |
|---|---------|--------------|----|-----|-----|-----|-------|---|
| u | 'G3IYII | veillication | ดจ | hei | ILU | LIN | UITJ | |

| Technical data for design verification Rated operational current for specified heat dissipation Heat dissipation per pole, current-dependent Equipment heat dissipation, current-dependent Static heat dissipation, non-current-dependent Heat dissipation capacity Operating ambient temperature min. Operating ambient temperature max. IEC/EN 61439 design verification 10.2 Strength of materials and parts | I _n P _{vid} P _{vid} P _{vs} P _{diss} | A W W W | 650 0 25 25 |
|---|--|------------------|--|
| Heat dissipation per pole, current-dependent Equipment heat dissipation, current-dependent Static heat dissipation, non-current-dependent Heat dissipation capacity Operating ambient temperature min. Operating ambient temperature max. IEC/EN 61439 design verification | P _{vid} P _{vid} P _{vs} | w w w | 0 25 25 |
| Equipment heat dissipation, current-dependent Static heat dissipation, non-current-dependent Heat dissipation capacity Operating ambient temperature min. Operating ambient temperature max. IEC/EN 61439 design verification | P _{vid} | W W | 25 25 |
| Static heat dissipation, non-current-dependent Heat dissipation capacity Operating ambient temperature min. Operating ambient temperature max. IEC/EN 61439 design verification | P _{vs} | w w | 25 |
| Heat dissipation capacity Operating ambient temperature min. Operating ambient temperature max. IEC/EN 61439 design verification | | W | |
| Operating ambient temperature min. Operating ambient temperature max. IEC/EN 61439 design verification | P _{diss} | | 0 |
| Operating ambient temperature max. IEC/EN 61439 design verification | | 0.0 | |
| IEC/EN 61439 design verification | | ··· | -30 |
| • | | °C | 50 |
| 10.2 Strength of materials and parts | | | |
| | | | |
| 10.2.2 Corrosion resistance | | | Meets the product standard's requirements. |
| 10.2.3.1 Verification of thermal stability of enclosures | | | Meets the product standard's requirements. |
| 10.2.3.2 Verification of resistance of insulating materials to normal heat | | | Meets the product standard's requirements. |
| 10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects | | | Meets the product standard's requirements. |
| 10.2.4 Resistance to ultra-violet (UV) radiation | | | Meets the product standard's requirements. |
| 10.2.5 Lifting | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.6 Mechanical impact | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.2.7 Inscriptions | | | Meets the product standard's requirements. |
| 10.3 Degree of protection of ASSEMBLIES | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.4 Clearances and creepage distances | | | Meets the product standard's requirements. |
| 10.5 Protection against electric shock | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.6 Incorporation of switching devices and components | | | Does not apply, since the entire switchgear needs to be evaluated. |
| 10.7 Internal electrical circuits and connections | | | Is the panel builder's responsibility. |
| 10.8 Connections for external conductors | | | Is the panel builder's responsibility. |
| 10.9 Insulation properties | | | |
| 10.9.2 Power-frequency electric strength | | | Is the panel builder's responsibility. |
| 10.9.3 Impulse withstand voltage | | | Is the panel builder's responsibility. |
| 10.9.4 Testing of enclosures made of insulating material | | | Is the panel builder's responsibility. |
| 10.10 Temperature rise | | | The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices. |
| 10.11 Short-circuit rating | | | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |
| 10.12 Electromagnetic compatibility | | | Is the panel builder's responsibility. The specifications for the switchgear must be observed. |
| 10.13 Mechanical function | | | The device meets the requirements, provided the information in the instruction leaflet (IL) is observed. $\label{eq:condition}$ |

Technical data ETIM 6.0

Low-voltage industrial components (EG000017) / Soft starter (EC000640)

Electric engineering, automation, process control engineering / Low-voltage switch technology / Load breakout, motor breakout / Semiconductor motor controller or soft starter (ecl@ss8.1-27-37-09-07 [ACO300008])

| (ecl@ss8.1-27-37-09-07 [AC0300008]) | | | | |
|---|----|---|-----------|--|
| Rated operation current le at 40 °C Tu | А | | 650 | |
| Rated operating voltage Ue | V | | 200 - 690 | |
| Rated power three-phase motor, inline, at 230 V | kV | W | 200 | |
| Rated power three-phase motor, inline, at 400 V | kV | W | 315 | |
| Rated power three-phase motor, inside delta, at 230 V | kV | W | 200 | |
| Rated power three-phase motor, inside delta, at 400 V | kV | W | 630 | |
| Internal bypass | | | Yes | |
| With display | | | Yes | |
| Torque control | | | No | |
| Rated surrounding temperature without derating | °C | C | 50 | |
| Rated control supply voltage Us at AC 50HZ | V | | 0 - 0 | |
| Rated control supply voltage Us at AC 60HZ | V | | 0 - 0 | |
| Rated control supply voltage Us at DC | V | | 24 - 24 | |
| Voltage type for actuating | | | DC | |

Approvals

| • • | |
|-----------------------------|--------------------------------------|
| Product Standards | IEC/EN 60947-4-2; UL 508; CE marking |
| UL File No. | E202571 |
| UL Category Control No. | NMFT |
| North America Certification | UL listed |
| Suitable for | Branch Circuits, not as BCPD |
| Max. Voltage Rating | 690 Vac |
| Degree of Protection | IP20 with kit |

Dimensions



