

Variable Frequency Drive, 1-/3- 230 V, 2.3 A, 0.37 kW, EMC-Filter

Powering Business Worldwide*

Part no. DC1-122D3FN-A66N Article no. 169241 Catalog No. DC1-122D3FN-A66N

Technical data General

General			
Standards			Specification for general requirements: IEC/EN 61800-2 EMC requirements: IEC/EN 61800-3 Safety requirements: IEC/EN 61800-5-1
Certifications			CE, UL, cUL, c-Tick, UkrSepro, EAC
Production quality			RoHS, ISO 9001
Climatic proofing	ρ_{W}	%	< 95%, average relative humidity (RH), non-condensing, non-corrosive
Ambient temperature			
operation (150 % overload)	θ	°C	-10 - +40
Storage	θ	°C	-40 - +60
Radio interference level			
Radio interference class (EMC)			C1, C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary.
Environment (EMC)			1st and 2nd environments as per EN 61800-3
maximum motor cable length	I	m	C1 ≤ 1 m C2 ≤ 5 m C3 ≤ 25 m
Mounting position			Vertical
Altitude		m	0 - 1000 m above sea level Above 1000 m: 1% derating for every 100 m max. 4000 m
Degree of Protection			IP66/NEMA 4X
Protection against direct contact			BGV A3 (VBG4, finger- and back-of-hand proof)
Main circuit			
Supply			200110
Rated operational voltage	U _e		230 V AC, 1-phase 240 V AC, single-phase
Mains voltage (50/60Hz)	U_{LN}	V	200 (-10%) - 240 (+10%)
Input current (150% overload)	I _{LN}	Α	3.7
System configuration			AC supply systems with earthed center point
Supply frequency	f_{LN}	Hz	50/60
Frequency range	f_{LN}	Hz	48 - 62
Mains switch-on frequency			Maximum of one time every 30 seconds
Power section			
Function			Frequency inverter with internal DC link and IGBT inverter
Overload current (150% overload)	IL	Α	3.45
max. starting current (High Overload)	I _H	%	175
Note about max. starting current			for 2 seconds every 20 seconds
Output voltage with V _e	U ₂		230 V AC, 3-phase 240 V AC, 3-phase
Output Frequency	f ₂	Hz	0 - 50/60 (max. 500)
Switching frequency	f _{PWM}	kHz	16 adjustable 4 - 32 (audible)
Operation Mode			U/f control Speed control with slip compensation
Frequency resolution (setpoint value)	Δf	Hz	0.1
Rated operational current			
At 150% overload	I _e	Α	2.3
Note			Rated operational current at a switching frequency of 16 kHz and an ambient air temperature of +40 °C
Power loss			

Reference voltage Us V 10 V DC (max. 10 mA) 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA 1, parameterizable, 0 - 10 V 4, parameterizable, max. 30 V DC Digital outputs Digital outputs Relay outputs Interface/field bus (built-in) V 10 V DC (max. 10 mA) 1, parameterizable, 0 - 10 V DC, 0/4 - 20 mA 1, parameterizable, max. 30 V DC 1, parameterizable, 24 V DC 1, parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) OP-Bus (RS485)/Modbus RTU, CANopen®				
Maximum leakage current to ground (PE) without motor of light Filted with Filtd with Filted	Heat dissipation at rated operational current I $_{\rm e}$ =150 $\%$	P_V	W	18.5
Fitted with	Efficiency	η	%	95
Frame size	Maximum leakage current to ground (PE) without motor	I _{PE}	mA	2.49
Motor feeder Note Common internally and externally wind externally wi	Fitted with			
Note	Frame size			FS1
Note	Motor feeder			
Note kW 0.37 Note at 220 - 240 V, 60 Hz 150 % Overload P HP by 20 - 240 V, 60 Hz 150 % Overload P HP By 20 - 240 V, 60 Hz 150 % Overload P HP By 20 - 240 V, 60 Hz maximum permissible cable length Imaximum permissible cable length Secreted, with motor choke: 150 unscreened, vist motor choke: 150 unscreened, vist	Note			
150 % Overload	Note			Overload cycle for 60 s every 600 s
Note 4 t 220 - 240 V, 60 Hz 150 % Overload P HP 0.5 maximum permissible cable length I MP screened: 50 Apparent power I WW screened, with motor choke: 150 Apparent power at rated operation 230 V S kVA 0.92 Apparent power at rated operation 240 V S kVA 0.96 Braking function F WW 0.96 Standed braking torque max. 30 % M _N 0.94 Ob braking torque max. 30 % M _N 0.94 Control section max. 30 % M _N 0.94 Reference voltage V 10 V OC (max. 10 mA) Analog inputs 1, parametrizable, 0 - 10 V OC, 04 - 20 mA Analog inputs 1, parametrizable, 0 - 10 V OC, 04 - 20 mA Analog outputs 1, parametrizable, 0 - 10 V OC, 04 - 20 mA Relay outputs 1, parametrizable, 0 - 10 V OC, 04 - 20 mA Relay outputs 1, parametrizable, 0 - 10 V OC, 04 - 20 mA Relay outputs 1, parametrizable, 0 - 10 V OC, 04 - 20 mA Relay outputs 5 1, parametrizab	Note			at 230 V, 50 Hz
150 % Overload	150 % Overload	P	kW	0.37
maximum permissible cable length land with mature choke: 150 screened, with motor choke: 150 unscreened, wit	Note			at 220 - 240 V, 60 Hz
Apparent power Apparent power at rated operation 230 V S KVA 0.96 Braking function S tandard braking torque C tortrol section Reference voltage Analog outputs Analog inputs Analog i	150 % Overload	Р	HP	0.5
Apparent power at rated operation 230 V S kVA 0.92 Apparent power at rated operation 240 V S kVA 0.96 Braking function Standard braking torque Ob traking torque Control section Reference voltage Analog inputs Analog outputs Digital inputs Digital inputs Digital outputs Reference voltage Light of the will bus (built-in) Assigned switching and protective elements Power Wiring □EC (Type B, gG), 150 % U(Class CC or J) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder ■ 150 % overload (CT/l _H , at 50 °C) Motor feeder	maximum permissible cable length	I	m	screened, with motor choke: 100 unscreened: 75
Apparent power at rated operation 240 V Braking function Standard braking torque DC braking torque DC braking torque TO braking to 100 % TO braki	Apparent power			
Braking function Standard braking torque DC braking torque DC braking torque Control section Reference voltage Analog inputs Analog inputs Analog outputs Digital inputs Digital outputs Digital outputs Digital outputs Reference voltage ERelay outputs Digital outputs Relay outputs Digital outputs Relay o	Apparent power at rated operation 230 V	S	kVA	0.92
Standard braking torque DC braking torque Control section Reference voltage Analog inputs Analog outputs Digital inputs Analog outputs Digital outputs Digital outputs Relay out	Apparent power at rated operation 240 V	S	kVA	0.96
DC braking torque adjustable to 100 % Control section Reference voltage Us 10 V DC (max. 10 mA) Analog inputs 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog outputs 1, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Digital inputs 4, parameterizable, 0 - 10 V DC Belay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 1, parameterizable, 0 - 10 V DC Relay outputs 2, parameterizable, 0 - 10 V DC Relay outputs 3, parameterizable, 0 - 10 V DC Relay outputs 3, parameterizable, 0 - 10 V DC Relay outputs 3, parameterizable, 0 - 10 V DC Relay outputs 3, parameterizable, 0 - 10 V DC Relay outputs 3, parameterizable, 0 - 10 V DC Relay outputs 3, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 10 V DC Relay outputs 4, parameterizable, 0 - 1	Braking function			
Control section Reference voltage Analog inputs Analog outputs Analog outputs Digital inputs Relay outputs Relay output	Standard braking torque			max. 30 % M _N
Reference voltage Us V 10 V DC (max. 10 mA) 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA 1, parameterizable, 0 - 10 V DC, 0/4 - 20 mA 1, parameterizable, 0 - 10 V 1, parameterizable, 0 - 10 V 1, parameterizable, 0 - 10 V 1, parameterizable, max. 30 V DC 1, parameterizable, 24 V DC 1, parameterizable, 24 V DC 1, parameterizable, N/0, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, N/0, 6 A (250 V, AC-1) / 5 A (30 V, D	DC braking torque			adjustable to 100 %
Analog inputs Analog outputs Analog outputs Digital inputs Digital outputs Digital outputs Digital outputs Digital outputs Digital outputs Relay outputs Relay outputs Relay outputs Digital outputs Relay outputs Digital outputs Relay outputs Digital outputs Relay outputs Digital on Digital on Digital on Digital on Digital on Digital outputs Digital on Digital output Digital on Digital on Digital on Digital on Digital on Digital output Digital on Digital on Digital output Digital on Digital output Digital On Digita	Control section			
Analog outputs Digital inputs A, parameterizable, 0 - 10 V A, parameterizable, max. 30 V DC Digital outputs Relay outputs Relay outputs Interface/field bus (built-in) Assigned switching and protective elements Power Wiring IEC (Type B, gG), 150 % UL (Class CC or J) A 10 Motor feeder 150 % overload (CT//H, at 50 °C) 1, parameterizable, 0 - 10 V A, parameterizable, max. 30 V DC 1, parameterizable, 24 V DC 1, parameterizable, 24 V DC 1, parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) 10 P-Bus (RS485)/Modbus RTU, CANopen® 1 PAZ-B10/IN A 10 DX-LN1-006 DX-LN1-006 DX-LN1-006 DX-LN3-005	Reference voltage	U_s	V	10 V DC (max. 10 mA)
Digital inputs A, parameterizable, max. 30 V DC 1, parameterizable, 24 V DC Relay outputs Interface/field bus (built-in) Assigned switching and protective elements Power Wiring IEC (Type B, gG), 150 % UL (Class CC or J) 150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) A, parameterizable, max. 30 V DC 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1) / 5 A (30 V, DC-1) 1, parameterizable, Mc. 250 V, AC-1)	Analog inputs			2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA
Digital outputs Relay outputs Interface/field bus (built-in) Assigned switching and protective elements Power Wiring IEC (Type B, gG), 150 % UL (Class CC or J) UL (Class CC or J) A 10 150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) Interface/field bus (built-in) Interface/field bus (built-in) I, parameterizable, 24 V DC Interface/field bus (250 V, AC-1) / 5 A (30 V, DC-1) Interface/field bus (built-in) Interface/field bus (built-in) I, parameterizable, 24 V DC I, parameterizable, 24 V DC Interface/field bus (250 V, AC-1) / 5 A (30 V, DC-1) Interface/field bus (built-in) Interface/field bus	Analog outputs			1, parameterizable, 0 - 10 V
Relay outputs Interface/field bus (built-in) Assigned switching and protective elements Power Wiring IEC (Type B, gG), 150 % UL (Class CC or J) 150 % overload (CT/I _H , at 50 °C) ISO % overload (CT/I _H , at 50 °C) Interface/field bus (built-in) 1, parameterizable, N/0, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) Power Wiring FAZ-B10/IN A 10 DX-LN1-006 DX-LN1-006 DX-LN1-006 DX-LN3-005	Digital inputs			4, parameterizable, max. 30 V DC
Interface/field bus (built-in) Assigned switching and protective elements Power Wiring IEC (Type B, gG), 150 % UL (Class CC or J) 150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) DX-LM3-005	Digital outputs			1, parameterizable, 24 V DC
Assigned switching and protective elements Power Wiring IEC (Type B, gG), 150 % UL (Class CC or J) A 10 150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) DX-LM3-005	Relay outputs			1, parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1)
Power Wiring FAZ-B10/1N IEC (Type B, gG), 150 % A 10 UL (Class CC or J) A DX-LN1-006 Motor feeder 50 % overload (CT/I _H , at 50 °C) DX-LN3-005 150 % overload (CT/I _H , at 50 °C) DX-LM3-005	Interface/field bus (built-in)			OP-Bus (RS485)/Modbus RTU, CANopen®
IEC (Type B, gG), 150 % FAZ-B10/1N UL (Class CC or J) A 10 150 % overload (CT/I _H , at 50 °C) DX-LN1-006 Motor feeder 50 % overload (CT/I _H , at 50 °C) DX-LM3-005	Assigned switching and protective elements			
UL (Class CC or J) A 10 150 % overload (CT/I _H , at 50 °C) DX-LN1-006 Motor feeder 50 % overload (CT/I _H , at 50 °C) DX-LM3-005	Power Wiring			
150 % overload (CT/I _H , at 50 °C) Motor feeder 150 % overload (CT/I _H , at 50 °C) DX-LN1-006 DX-LN1-006	IEC (Type B, gG), 150 %			FAZ-B10/1N
Motor feeder 150 % overload (CT/I _H , at 50 °C) DX-LM3-005	UL (Class CC or J)		Α	10
150 % overload (CT/I _H , at 50 °C) DX-LM3-005	150 % overload (CT/I _H , at 50 °C)			DX-LN1-006
	Motor feeder			
150 % overload (CT/I _H , at 50 °C) DX-SIN3-004	150 % overload (CT/I _H , at 50 °C)			DX-LM3-005
	150 % overload (CT/I _H , at 50 °C)			DX-SIN3-004

Design verification as per IEC/EN 61439

In	Α	2.3
P _{vid}	W	0
P _{vid}	W	18.5
P_{vs}	W	0
P _{diss}	W	0
	°C	-10
	°C	40
		Meets the product standard's requirements.
		Meets the product standard's requirements.
		Meets the product standard's requirements.
t		Meets the product standard's requirements.
	P _{vid} P _{vid} P _{vs}	P _{vid} W P _{vid} W P _{vs} W P _{diss} W °C °C

10.2.4 Resistance to ultra-violet (UV) radiation	Meets the product standard's requirements.
10.2.5 Lifting	Does not apply, since the entire switchgear needs to be evaluated.
10.2.6 Mechanical impact	Does not apply, since the entire switchgear needs to be evaluated.
10.2.7 Inscriptions	Meets the product standard's requirements.
10.3 Degree of protection of ASSEMBLIES	Does not apply, since the entire switchgear needs to be evaluated.
10.4 Clearances and creepage distances	Meets the product standard's requirements.
10.5 Protection against electric shock	Does not apply, since the entire switchgear needs to be evaluated.
10.6 Incorporation of switching devices and components	Does not apply, since the entire switchgear needs to be evaluated.
10.7 Internal electrical circuits and connections	Is the panel builder's responsibility.
10.8 Connections for external conductors	Is the panel builder's responsibility.
10.9 Insulation properties	
10.9.2 Power-frequency electric strength	Is the panel builder's responsibility.
10.9.3 Impulse withstand voltage	Is the panel builder's responsibility.
10.9.4 Testing of enclosures made of insulating material	Is the panel builder's responsibility.
10.10 Temperature rise	The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.
10.11 Short-circuit rating	Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.12 Electromagnetic compatibility	Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.13 Mechanical function	The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

Technical data ETIM 6.0

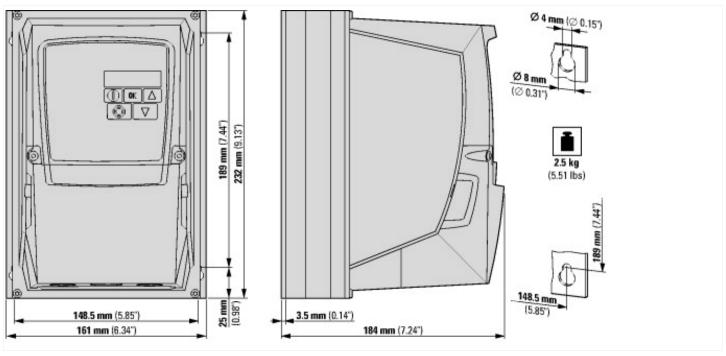
Low-voltage industrial components (EG000017) / Frequency converter =< 1 kV	(EC001857)		
Electric engineering, automation, process control engineering / Electrical driv	e / Static frequency conve	erter / Static frequency converter = < 1 kv (ecl@ss8.1-27-02-31-01 [AKE17701	1])
Mains voltage	V	200 - 240	
Mains frequency		50/60 Hz	
Number of phases input		1	
Number of phases output		3	
Max. output frequency	Hz	500	
Max. output voltage	V	230	
Rated output current I2N	A	2.3	
Max. output at quadratic load at rated output voltage	kW	0.37	
Max. output at linear load at rated output voltage	kW	0.37	
With control unit		Yes	
Application in industrial area permitted		Yes	
Application in domestic- and commercial area permitted		Yes	
Supporting protocol for TCP/IP		No	
Supporting protocol for PROFIBUS		No	
Supporting protocol for CAN		Yes	
Supporting protocol for INTERBUS		No	
Supporting protocol for ASI		No	
Supporting protocol for KNX		No	
Supporting protocol for MODBUS		Yes	
Supporting protocol for Data-Highway		No	
Supporting protocol for DeviceNet		No	
Supporting protocol for SUCONET		No	
Supporting protocol for LON		No	
Supporting protocol for PROFINET IO		No	
Supporting protocol for PROFINET CBA		No	
Supporting protocol for SERCOS		No	
Supporting protocol for Foundation Fieldbus		No	
Supporting protocol for EtherNet/IP		No	
Supporting protocol for AS-Interface Safety at Work		No	
Supporting protocol for DeviceNet Safety		No	
Supporting protocol for INTERBUS-Safety		No	

Supporting protocol for PROFIsafe		No
Supporting protocol for SafetyBUS p		No
Supporting protocol for other bus systems		No
Number of HW-interfaces industrial Ethernet		0
Number of HW-interfaces PROFINET		0
Number of HW-interfaces RS-232		0
Number of HW-interfaces RS-422		0
Number of HW-interfaces RS-485		1
Number of HW-interfaces serial TTY		0
Number of HW-interfaces USB		1
Number of HW-interfaces parallel		0
Number of HW-interfaces other		0
With optical interface		No
With PC connection		Yes
Integrated breaking resistance		No
4-quadrant operation possible		No
Type of converter		U converter
Degree of protection (IP)		IP66
Height	mm	184
Width	mm	81
Depth	mm	124
Relative symmetric net frequency tolerance	%	10
Relative symmetric net current tolerance	%	10

Approvals

Product Standards	UL 508C; CSA-C22.2 No. 14; IEC/EN61800-3; IEC/EN61800-5; CE marking
UL File No.	E172143
UL Category Control No.	NMMS, NMMS7
CSA File No.	UL report applies to both US and Canada
North America Certification	UL listed, certified by UL for use in Canada
Specially designed for North America	No
Suitable for	Branch circuits
Max. Voltage Rating	1~ 240 V AC IEC: TN-S UL/CSA: "Y" (Solidly Grounded Wey)
Degree of Protection	IEC: IP66

Dimensions



Additional product information (links) IL04020013Z DC1 variable frequency drives (FS1 - FS3, IP66) IL04020013Z DC1 variable frequency drives (FS1 ftp://ftp.moeller.net/DOCUMENTATION/AWA_INSTRUCTIONS/IL04020013Z2016_07.pdf - FS3, IP66) MN04020003Z DC1 variable frequency drives, Installation manual MN04020003Z Frequenzumrichter DC1, ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020003Z_DE.pdf Handbuch - Deutsch MN04020003Z DC1 variable frequency drive, ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020003Z_EN.pdf manual - English MN04020003Z Frekvenční měnič DC1, manuál ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020003Z_CZ.pdf čeština ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020003Z_IT.pdf MN04020003Z Convertitori di frequenza DC1, manuale - italiano MN04020004Z DC1 variable frequency drives, Parameters manual MN04020004Z DC1 variable frequency drives, ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020004Z_DE.pdf Parameters manual - Deutsch MN04020004Z DC1 variable frequency drives, ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020004Z_EN.pdf Parameters manual - English

http://www.eaton.eu/DE/ecm/groups/public/@pub/@europe/@electrical/documents/content/pct_1095238_de.pdf

CA04020001Z-DE Sortimentskatalog:

starten und steuern

Antriebstechnik effizient gestalten, Motoren

5/5